

Kernel Method: Data Analysis with Positive Definite Kernels

7. Mean on RKHS and characteristic class

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Outline

1. Introduction
2. Mean on RKHS
3. Characteristic kernel

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3. Characteristic kernel

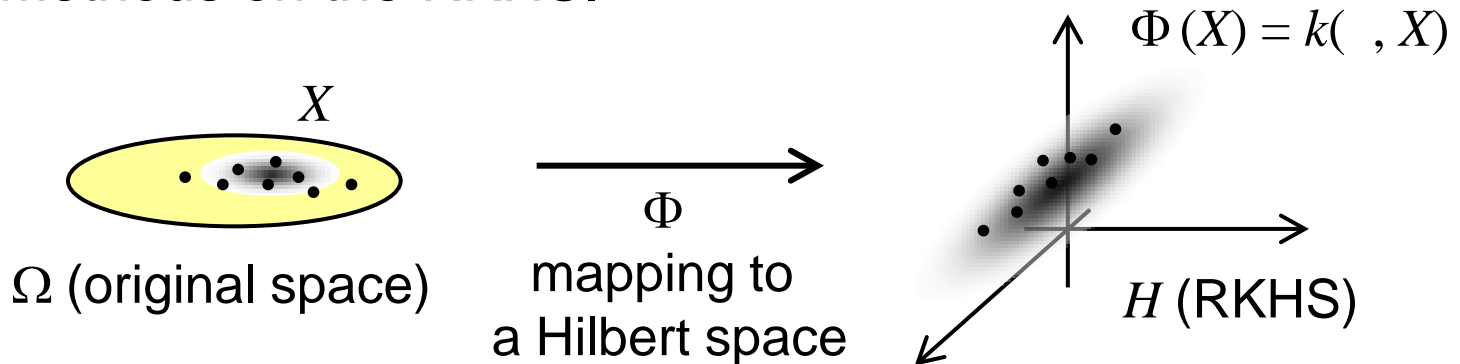
Introduction

- Kernel methods for statistical inference

- We have seen that positive definite kernels are used for capturing ‘nonlinearity’ or ‘high-order moments’ of original data.

e.g. Support vector machine, kernel PCA, kernel CCA, etc.

- Kernelization: mapping data into a RKHS and apply linear methods on the RKHS.



- Consider more basic statistics!

- Consider basic statistics (mean, variance, ...) on RKHS, and **their meaning on the original space.**

- Basic statistics
on Euclidean space

- Mean

- Covariance

- Conditional covariance

- Basic statistics
on RKHS

- Mean

- Cross-covariance operator

- Conditional-covariance operator

Outline

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2. Mean on RKHS
3. Characteristic kernel

Mean on RKHS I

(X, \mathcal{B}) : measurable space.

X : random variable taking value on X .

k : measurable positive definite kernel on X .

H : RKHS defined by k .

$\Phi(X) = k(\cdot, X)$: random variable on RKHS.

- Assume $E[\sqrt{k(X, X)}] < \infty$. (satisfied by a bounded kernel)
- We want to define the mean $E[\Phi(X)]$ of $\Phi(X)$ on H .

It can be defined as the integral of a Hilbert-valued function.

Mean on RKHS II

- Alternative definition:

Define the **mean** of X on H by $m_X \in H$ that satisfies

$$\langle m_X, f \rangle = E[f(X)] \quad (\forall f \in H)$$

- Intuition:

Sample mean $\hat{m}_X(u) = \frac{1}{N} \sum_{i=1}^N \Phi(X_i)$

$$\langle \hat{m}_X, f \rangle = \frac{1}{N} \sum_{i=1}^N f(X_i) \quad \rightarrow \quad \langle m_X, f \rangle = E[f(X)]$$

- Explicit form:

$$m_X(u) = E[k(u, X)] = \int k(u, x) dP(x)$$

$$\therefore m_X(u) = \langle m_X, k(\cdot, u) \rangle = E[k(X, u)].$$

We call $m_X(u)$ **kernel mean**.

Mean on RKHS III

– Fact:

$$\langle E[k(\cdot, X)], f \rangle = E[\langle k(\cdot, X), f \rangle]$$

(exchangeability)

– The kernel mean does exist uniquely.

Existence and uniqueness:

$$|E[f(X)]| \leq E|\langle f, k(\cdot, X) \rangle| \leq \|f\| E\|k(\cdot, X)\| = E[\sqrt{k(X, X)}] \|f\|.$$

$f \mapsto E[f(X)]$ is a bounded linear functional on H .

Use Riesz's lemma.

Mean on RKHS IV

- Intuition: the mean contains the information of the **high-order moments**.

X : \mathbf{R} -valued random variable. k : pos.def. kernel on \mathbf{R} .

Suppose pos. def. kernel k admits a power-series expansion on \mathbf{R} .

$$k(u, x) = c_0 + c_1(xu) + c_2(xu)^2 + \dots \quad (c_i > 0)$$

e.g.) $k(x, u) = \exp(xu)$

The mean m_X works as a moment generating function:

$$m_X(u) = E[k(u, X)] = c_0 + c_1 E[X]u + c_2 E[X^2]u^2 + \dots$$

$$\frac{1}{c_\ell} \frac{d^\ell}{du^\ell} m_X(u) \Big|_{u=0} = E[X^\ell]$$

Characteristic Kernel I

\mathcal{P} : family of all the probabilities on a measurable space (Ω, \mathcal{B}) .

H : RKHS on Ω with a bounded measurable kernel k .

m_P : mean on H for a probability $P \in \mathcal{P}$

Def. The kernel k is called **characteristic** (w.r.t. \mathcal{P}) if the mapping

$$\mathcal{P} \rightarrow H, \quad P \mapsto m_P$$

is one-to-one.

- The kernel mean by a characteristic kernel uniquely determines a probability.

$$m_P = m_Q \iff P = Q$$

i.e.

$$E_{X \sim P}[k(u, X)] = E_{X \sim Q}[k(u, X)] \iff P = Q$$

Characteristic Kernel II

– Generalization of **characteristic function**

With Fourier kernel $k_F(x, y) = \exp(\sqrt{-1} x^T y)$

$$\text{Ch.f.}_X(u) = E[k_F(X, u)].$$

- The characteristic function uniquely determines a Borel probability on \mathbf{R}^m .
- The kernel mean $m_X(u) = E[k(u, X)]$ by a characteristic kernel uniquely determines a probability on (Ω, \mathcal{B}) .
Note: Ω may not be Euclidean.

Characteristic Kernel III

- The characteristic RKHS must be large enough!

Examples for \mathbf{R}^m (proved later)

- Gaussian RBF kernel

$$k_G(x, y) = \exp\left(-\frac{1}{2\sigma^2} \|x - y\|^2\right)$$

- Laplacian kernel

$$k_L(x, y) = \exp\left(-\alpha \sum_{i=1}^m |x_i - y_i|\right)$$

- Polynomial kernels are **not** characteristic.
 - The RKHS for $(x^T y + c)^d$ is the space of polynomials of degree not greater than d .
 - The moments larger than d cannot be considered.

Empirical Estimation of Kernel Mean

- Empirical mean on RKHS

- An advantage of RKHS approach is its easy empirical estimation.

- $X^{(1)}, \dots, X^{(N)}$: i.i.d. sample

- $\Phi(X_1), \dots, \Phi(X_N)$: i.i.d. sample on RKHS

Empirical kernel mean: $\hat{m}_X^{(N)} = \frac{1}{N} \sum_{i=1}^N \Phi(X_i) = \frac{1}{N} \sum_{i=1}^N k(\cdot, X_i)$

The empirical kernel mean gives empirical average

$$\langle \hat{m}_X^{(N)}, f \rangle = \frac{1}{N} \sum_{i=1}^N f(X_i) \equiv \hat{E}_N[f(X)] \quad (\forall f \in H)$$

Asymptotic Properties I

Theorem (strong \sqrt{N} -consistency)

Assume $E[k(X, X)] < \infty$. For i.i.d. sample X_1, \dots, X_N ,

$$\|\hat{m}_X^{(N)} - m_X\| = O_p(1/\sqrt{N}) \quad (N \rightarrow \infty)$$

Proof.

$$\begin{aligned} E\|\hat{m}_X^{(n)} - m_X\|^2 &= \frac{1}{n^2} \sum_{i=1}^n \sum_{j=1}^n E_{X_i} E_{X_j} [k(X_i, X_j)] \\ &\quad - \frac{2}{n} \sum_{i=1}^n E_{X_i} E_X [k(X_i, X)] + E_X E_{\tilde{X}} [k(X, \tilde{X})] \\ &= \frac{1}{n^2} \sum_{i=1}^n \sum_{j \neq i} E[k(X_i, X_j)] + \frac{1}{n} E_X [k(X, X)] - E_X E_{\tilde{X}} [k(X, \tilde{X})] \\ &= \frac{1}{n} \{E_X [k(X, X)] - E_X E_{\tilde{X}} [k(X, \tilde{X})]\}. \end{aligned}$$

By Chebychev's inequality,

$$\Pr(\sqrt{n}\|\hat{m}_X^{(n)} - m_X\| \geq \delta) \leq \frac{nE\|\hat{m}_X^{(n)} - m_X\|^2}{\delta^2} = \frac{C}{\delta^2}. \quad \square$$

Asymptotic Properties II

Corollary (Uniform law of large numbers)

Assume $E[k(X, X)] < \infty$. For i.i.d. sample X_1, \dots, X_N ,

$$\sup_{f \in H, \|f\| \leq 1} \left| \frac{1}{N} \sum_{i=1}^N f(X_i) - E[f(X)] \right| = O_p(1/\sqrt{N}) \quad (N \rightarrow \infty).$$

Proof.

$$LHS = \sup_{f \in H, \|f\| \leq 1} |\langle \hat{m}_X^{(N)} - m_X, f \rangle| = \|\hat{m}_X^{(N)} - m_X\|.$$

□

Note: $\sup_{\|f\| \leq 1} |\langle h, f \rangle| = \|h\|$

Asymptotic Properties III

Theorem (Convergence to Gaussian process)

Assume $E[k(X, X)] < \infty$.

$$\sqrt{N}(\hat{m}^{(N)} - m_X) \Rightarrow G \quad \text{in law} \quad (N \rightarrow \infty),$$

where G is a centered Gaussian process on H with the covariance function

$$C(f, g) = E[f(X)g(X)] - E[f(X)]E[g(X)] = \text{Cov}[f(X), g(X)].$$

Proof is omitted. See Berlinet & Thomas-Agnan, Theorem 108.

Application: Two-sample Problem

- Two-sample homogeneity test

Two i.i.d. samples are given;

$$X^{(1)}, \dots, X^{(N_X)} \quad \text{and} \quad Y^{(1)}, \dots, Y^{(N_Y)}.$$

Q: Are they sampled from the same distribution?

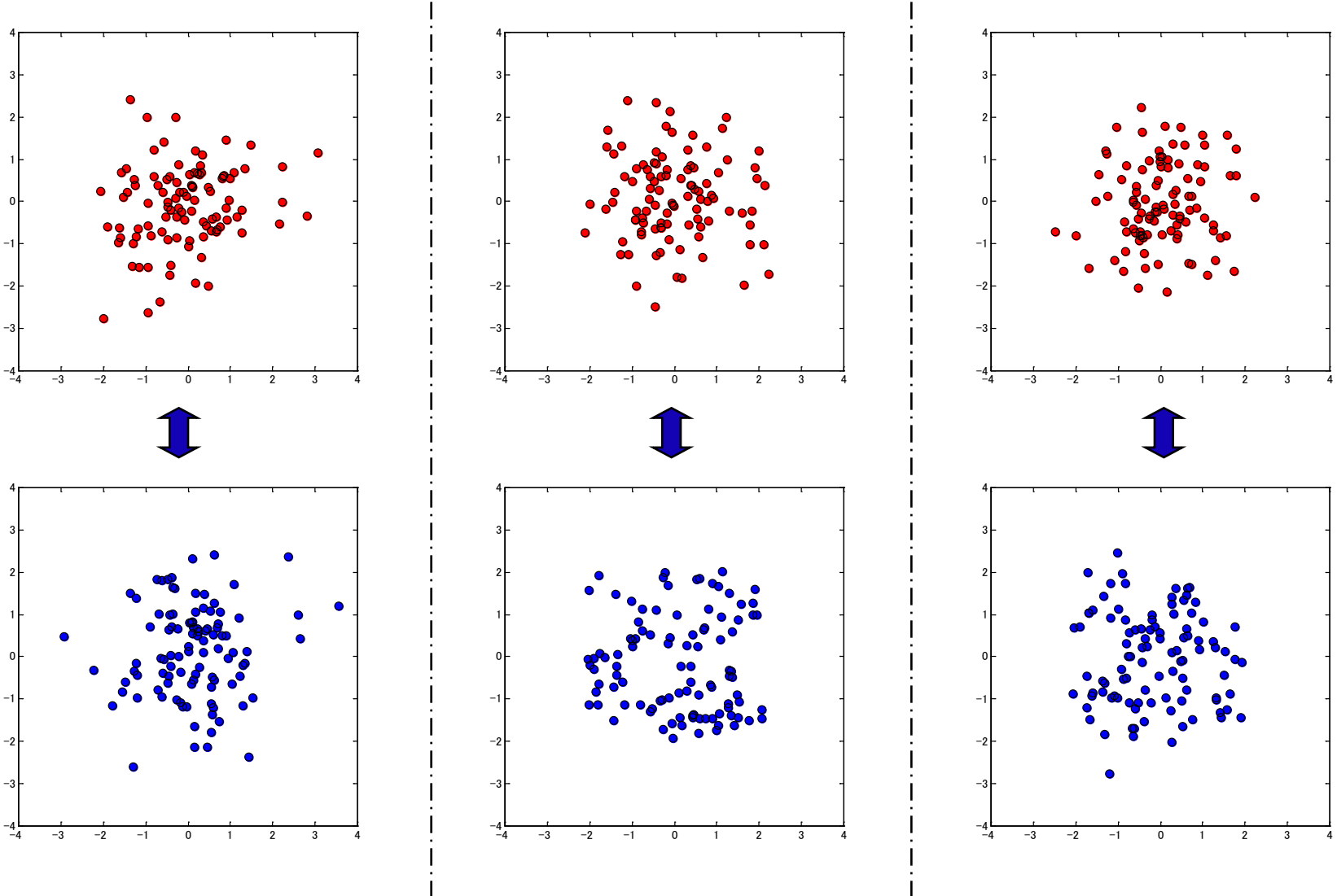
- Practically important.

We often wish to distinguish two things:

- Are the experimental results of treatment and control significantly different?
 - Were the plays “*Henry VI*” and “*Henry II*” written by the same author?
- Approach by kernel method: $m_X - m_Y$
Use the difference of means with a characteristic kernel.

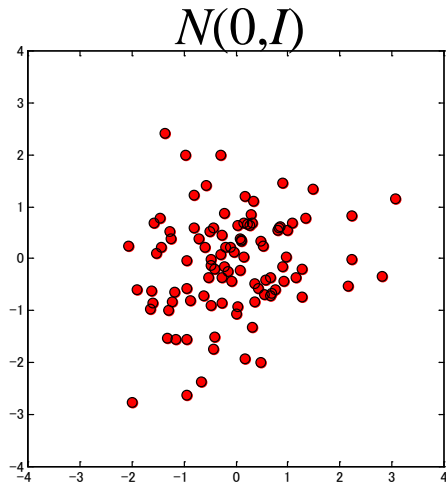
– Example: do they have the same distribution?

N = 100

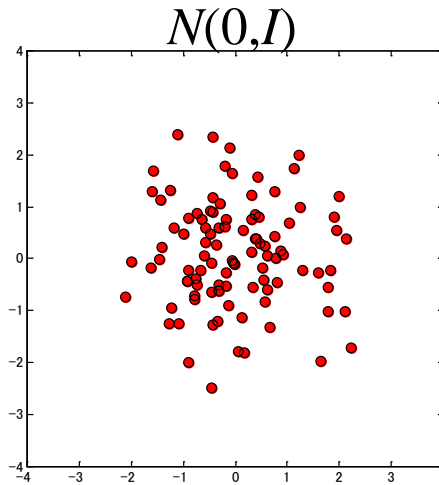
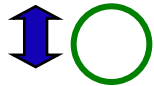


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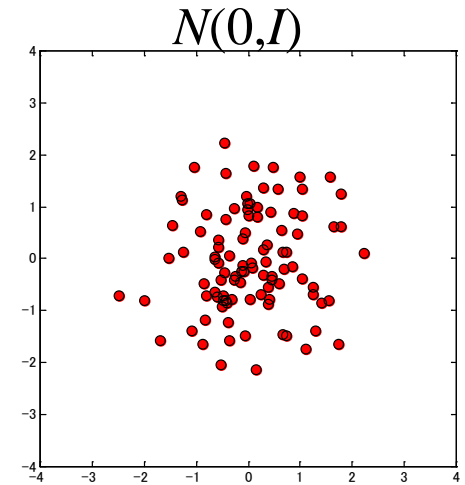
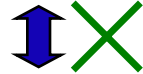
$N = 100$



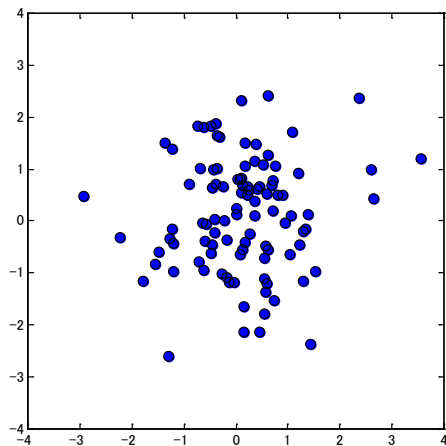
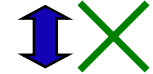
$N(0, I)$



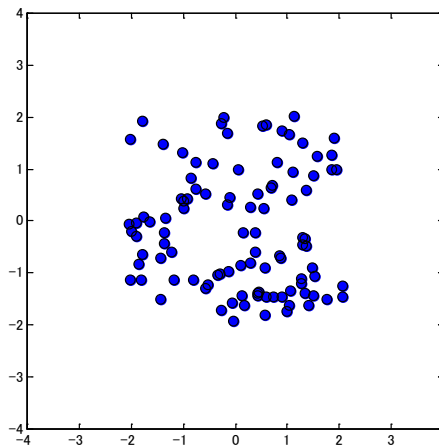
$N(0, I)$



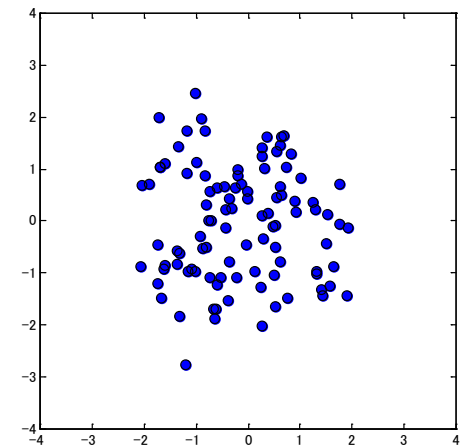
$N(0, I)$



$N(0, I)$



Unif



$0.5N(0, I) + 0.5Unif$

Kernel Method for Two-sample Problem

- Maximum Mean Discrepancy (Gretton et al 2007, NIPS19)

- In population

$$MMD^2 = \|m_X - m_Y\|_H^2$$

- Empirically

$$\begin{aligned} MMD_{emp}^2 &= \|\hat{m}_X - \hat{m}_Y\|_H^2 \\ &= \frac{1}{N_X^2} \sum_{i,j=1}^{N_X} k(X_i, X_j) - \frac{2}{N_X N_Y} \sum_{i=1}^{N_X} \sum_{a=1}^{N_Y} k(X_i, Y_a) + \frac{1}{N_Y^2} \sum_{a,b=1}^{N_Y} k(Y_a, Y_b) \end{aligned}$$

- With characteristic kernel, $MMD = 0$ if and only if $P_X = P_Y$.

- Asymptotic distribution of MMD_{emp}^2 is known.

After debias, it is U-statistics.

Example

– Two sample test

$$P: N(0, 1/3) \quad Q_a: a\phi(x; 0, 1/3) + (1-a)\frac{1}{2}I_{[-1,2]}(x).$$

Null hypothesis $H_0: P = Q_a$

Alternative $H_1: P \neq Q_a$

– Results

- Comparison with Kolmogorov-Smirnov test
- Significance level = 5%. The asymptotic distribution is used.

| | MMD | | | | | Kolmogorov-Smirnov | | | | |
|---------|-------|-------|-------|-------|-------|--------------------|-------|-------|-------|-------|
| N / a | 1 | 0.75 | 0.5 | 0.25 | 0 | 1 | 0.75 | 0.5 | 0.25 | 0 |
| 200 | 0.966 | 0.898 | 0.788 | 0.964 | 0.882 | 0.962 | 0.910 | 0.730 | 0.956 | 0.940 |
| 500 | 0.990 | 0.868 | 0.544 | 0.118 | 0.038 | 0.990 | 0.752 | 0.382 | 0.112 | 0.124 |
| 1000 | 0.986 | 0.976 | 0.704 | 0.088 | 0 | 0.954 | 0.950 | 0.796 | 0.316 | 0.002 |

Percentage of accepting homogeneity in 500 simulations

1. Introduction
2. Mean element in RKHS
3. Characteristic kernel

Conditions on Characteristic Kernels I

Theorem (FBJ08+)

k : bounded measurable positive definite kernel on a measurable space (Ω, \mathcal{B}) . H : associated RKHS. Then, k is characteristic if and only if $H + \mathbf{R}$ is dense in $L^2(P)$ for any probability P on (Ω, \mathcal{B}) .

Proof. See Appendix 1.

– The characteristic kernel must be large enough.

Def. A positive definite kernel on a compact space D is called **universal** if its RKHS is dense in $C(D)$.*

Proposition. A universal kernel is characteristic.

* $C(D)$ is the Banach space of the continuous function on D with sup norm.

Shift-invariant Characteristic Kernels II

- $\phi(x-y)$: continuous shift-invariant kernels on \mathbf{R}^m .

By Bochner's theorem, Fourier transform of ϕ is non-negative.

The characteristic kernels in this class are completely determined.

- Intuition:

- For a shift-invariant kernel, the kernel mean is **convolution**:

$$m_p(u) = E_p[k(u, X)] = \int \phi(u - x) dP(x) = (\phi * p)(u)$$

- The characteristic property is equivalent to

$$\phi * p = \phi * q \quad \Rightarrow \quad p = q.$$

or by Fourier transform,

$$\hat{\phi}(\hat{p} - \hat{q}) = 0 \quad \Rightarrow \quad p = q$$

- It is expected that if $\hat{\phi}(\omega) > 0$ at any ω , then the above condition holds.

Shift-invariant Characteristic Kernels II

Theorem (Sriperumbudur et al. 2008)

Let $k(x,y) = \phi(x-y)$ be a \mathbf{R} -valued continuous shift-invariant positive definite kernel on \mathbf{R}^m such that

$$\phi(x) = \int e^{\sqrt{-1}x^T \omega} d\Lambda(\omega).$$

Then, k is characteristic if and only if $\text{supp}(\Lambda) = \mathbf{R}^m$.

$$\text{supp}(\mu) = \{x \in \mathbf{R}^m \mid \mu(U) \neq 0 \text{ for all open set } U \text{ s.t. } x \in U\}$$

Example

Gaussian $\phi(x) = e^{-x^2/2\sigma^2}$ $\hat{\phi}(\omega) = e^{-\sigma^2\omega^2/2}$

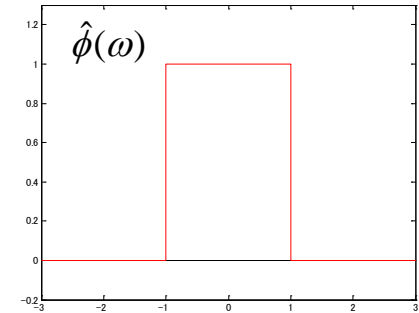
Laplacian $\phi(x) = e^{-\alpha|x|}$ $\hat{\phi}(\omega) = \frac{2\alpha}{\pi(\alpha^2 + x^2)}$

Cauchy $\phi(x) = \frac{2\alpha}{\pi(\alpha^2 + x^2)}$ $\hat{\phi}(\omega) = e^{-\alpha|\omega|}$

- if $\hat{\phi}(\omega) = 0$ on an interval of some frequency, then k must not be characteristic.

E.g. $\phi(x) = \frac{\sin(\alpha x)}{x}$ $\hat{\phi}(\omega) = \sqrt{\frac{\pi}{2}} I_{[-\alpha, \alpha]}(\omega)$

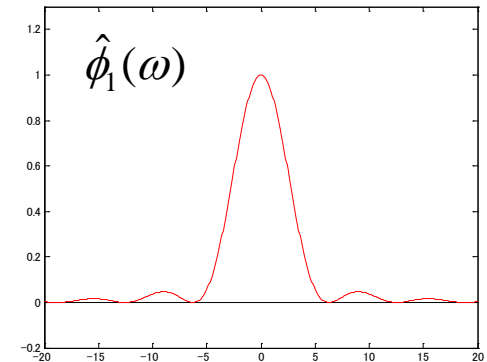
If $(p - q)^\wedge$ differ only out of $[-a, a]$,
 p and q are not distinguishable.



- B_{2n+1} -spline kernel **is** characteristic.

$$\phi_{2n+1}(x) = I_{[-\frac{1}{2}, \frac{1}{2}]} * \dots * I_{[-\frac{1}{2}, \frac{1}{2}]}$$

$$\hat{\phi}_{2n+1}(\omega) = \left(\frac{2}{\pi}\right)^{n+1} \frac{\sin^{2n+2}(\omega/2)}{\omega^{2n+2}}$$



- Bochner's theorem and the previous theorem can be extended to locally compact Abelian group.

Summary

- Mean on RKHS

- A random variable X can be transformed into a RKHS by

$$\Phi(X) = k(\cdot, X)$$

Its mean $m_X = E[\Phi(X)]$ contains the information of the higher-order moments of X .

- If the positive definite kernel is characteristic, the kernel mean element uniquely determines a probability.
- The kernel mean by characteristic kernel can be applied for two sample tests.
- The shift-invariant characteristic kernels on \mathbf{R}^m (and locally compact Abelian groups) is completely determined.

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Appendix 1: proof on the characteristic kernel

Proof.

\Leftarrow) Assume $m_P = m_Q$.

$|P - Q|$: the total variation of $P - Q$.

Since $H + \mathbf{R}$ is dense in $L^2(|P - Q|)$, for any $\varepsilon > 0$ and $A \in \mathcal{B}$ there exists $f \in H + \mathbf{R}$ and such that

$$\int |f - I_A| d(|P - Q|) < \varepsilon.$$

Thus, $|(E_P[f(X)] - P(A)) - (E_Q[f(X)] - Q(A))| < \varepsilon$.

From $m_P = m_Q$, $E_P[f(X)] = E_Q[f(X)]$, thus $|P(A) - Q(A)| < \varepsilon$.

This means $P = Q$.

\Rightarrow) Suppose $H + \mathbf{R}$ is not dense in $L^2(P)$.
There is $f \in L^2(P)$ ($f \neq 0$) such that

$$\int f(x)\varphi(x)dP(x) = 0 \quad (\forall \varphi \in H), \quad \int f(x)dP(x) = 0.$$

Let $c = 1/\|f\|_{L^1(P)}$.

Define probabilities Q_1 and Q_2 by

$$Q_1(E) = c \int_E (|f(x)| - f(x))dP(x), \quad Q_2(E) = c \int_E |f(x)|dP(x).$$

$Q_1 \neq Q_2$ from $f \neq 0$.

But,

$$E_{Q_2}[k(u, X)] - E_{Q_1}[k(u, X)] = c \int f(x)k(u, x)dP(x) = 0 \quad (\forall u)$$

which means k is not characteristic. \square

Appendix 2: Review of Fourier analysis

- Fourier transform of $f \in L^1(\mathbf{R}^\ell)$

$$\hat{f}(\omega) = \int f(x) e^{-\sqrt{-1}\omega^T x} dm_x \quad dm_x = \frac{1}{(2\pi)^{\ell/2}} dx$$

- Fourier inverse transform

$$\check{F}(x) = \int F(\omega) e^{\sqrt{-1}x^T \omega} dm_\omega$$

- Fourier transform of a bounded \mathbf{C} -valued Borel measure μ

$$\hat{f}(\omega) = \int e^{-\sqrt{-1}\omega^T x} d\mu(x)$$

- Convolution

$$f * g = \int f(x-y)g(y)dm_y = \int g(x-y)f(y)dm_y$$

$$\mu * g = \int f(x-y)d\mu(y)$$

- Fourier transform of convolution:

$$(\mu * g)^\wedge = \hat{\mu} \hat{g}$$

– Re: convolution $(f * g)^\wedge = \hat{f} \hat{g}$

Proof.

$$\begin{aligned}(f * g)^\wedge(\omega) &= \int e^{-\sqrt{-1}x^T \omega} \int f(x-y)g(y)dm_y dm_x \\ &= \int e^{-\sqrt{-1}(x-y)^T \omega} e^{-\sqrt{-1}y^T \omega} \int f(x-y)g(y)dm_y dm_x \\ &= \int e^{-\sqrt{-1}z^T \omega} e^{-\sqrt{-1}y^T \omega} \int f(z)g(y)dm_y dm_z \quad [z = x - y] \\ &= \int e^{-\sqrt{-1}z^T \omega} f(z)dm_z \int e^{-\sqrt{-1}y^T \omega} g(y)dm_y \\ &= \hat{f}(\omega)\hat{g}(\omega).\end{aligned}$$